| Discipline : MECHANICAL ENGG. | Semester : 5th | Name of the Teaching Faculty: Shubhajit Biswal |
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| Subject: MECHATRONICS (TH-4) | No. of days/per week class allotted: 04 | Semester From date: 01.07.2024 To Date: 08.11.2024 No. of Weeks: 15 |
| Week | Class Day | Theory Topics |
| 1 st | 1 st | INTRODUCTION TO MECHATRONICS Definition of Mechatronics |
| | 2 nd | Advantages & disadvantages of Mechatronics |
| | 3 rd | Application of Mechatronics |
| | 4 th | Scope of Mechatronics in Industrial Sector |
| 2 nd | 1 st | Components of a Mechatronics System Importance of mechatronics in automation |
| | 2 nd | SENSORS AND TRANSDUCERS Definition of Transducers. |
| | 3rd | Classification of Transducers |
| | 4 th | Classification of Transducers |
| 3rd | 1 st | Electromechanical Transducers |
| | 2 nd | Transducers Actuating Mechanisms |
| | 3 rd | Transducers Actuating Mechanisms |
| | 4 th | Displacement &Positions Sensors |
| 4 th | 1 st | Velocity, motion, force and pressure sensors |
| | 2 nd | Velocity, motion, force and pressure sensors |
| | 3rd | Temperature and light sensors |
| | 4 th | ACTUATORS-MECHANICAL, ELECTRICAL Mechanical Actuators |
| 5 th | 1st | Machine, Kinematic Link, Kinematic Pair |
| | 2nd | Mechanism, Slider crank Mechanism |
| | _ | |
| | 3 rd | Gear Drive, Spur gear, Bevel gear, Helical gear, worm gear |
| | 4 th | Belt & Belt drive Bearings |
| | 1 st | Electrical Actuator |
| | 2 nd | Switches and relay |
| 6 th | 3rd | Solenoid D.C Motors |
| | 4 th | A.C. Motors Stepper Motors |
| 7 th | 1 st | Specification and control of stepper motors Servo Motors D.C & A.C |
| | 2 nd | PROGRAMMABLE LOGIC CONTROLLERS(PLC) Introduction |
| | 3rd | Advantages of PLC |
| | 4 th | Advantages of PLC |
| 8 th | 1 st | Selection and uses of PLC |
| | 2nd | Selection and uses of PLC |
| | 3rd | Architecture basic internal structures |
| | 4 th | Architecture basic internal structures |
| 9th | 1st | Architecture basic internal structures |

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| | 2 nd | Input/output Processing and Programming |
|------------------|-----------------|--|
| | 3rd | Input/output Processing and Programming |
| | 4 th | Input/output Processing and Programming |
| 10 th | 1 st | Mnemonics |
| | 2 nd | Mnemonics |
| | 3rd | Master and Jump Controllers |
| | 4 th | Master and Jump Controllers |
| 11 th | 1 st | ELEMENTS OF CNC MACHINES Introduction to Numerical Control of machines and CAD/CAM |
| | 2 nd | NC machines CNC machines |
| | 3rd | CAD/CAM |
| | 4 th | Software and hardware for CAD/CAM |
| | 1 st | Functioning of CAD/CAM system |
| | | Features and characteristics of CAD/CAM system |
| anth | 2 nd | Application areas for CAD/CAM |
| 12 th | 3rd | Elements of CNC machines |
| | 4 th | Introduction Machine Structure |
| 13 th | 1st | Guide ways/Slide ways |
| | 2 nd | Introduction and Types of Guideways |
| | 3rd | Factors of design of guideways |
| | 4th | Drives |
| 14 th | 1st | Spindle drives |
| | 2 nd | Feed drive |
| | 3rd | Spindle and Spindle Bearings |
| | 4 th | ROBOTICS Definition, Function and laws of robotics Types of industrial robots |
| 15 th | 1 st | Definition, Function and laws of robotics Types of industrial robots |
| | 2 nd | Robotic systems |
| | 3rd | Robotic systems |
| | 4 th | Advantages and Disadvantages of robots |

Learning Resouces:

01. Mechatronics by W. Bolton, Pearson Education India

02. Text book of Mechatronics by R.K Rajput, S.Chand

03. CAD/CAM/CIM by R.RADHAKRISHNA, S, SUBRAMANIAN, NEW AGE INTERNATIONAL PVT, LTD

04. CAD/CAM by MIKELLGROVER

29.06.24

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